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Uniform Circular Motion and Simple Harmonic Motion

Angular Position (θ)

$$\theta = \omega t$$

$\omega =$ angular speed ($\frac{\text{rad}}{\text{s}}$)

$t =$ time (s)

In SHM ω is angular frequency

$$\omega = 2\pi f = \frac{2\pi}{T}$$

SHM position (x)

$$x = A \cos\left(\frac{2\pi}{T} t\right)$$

$$x = A \cos(\omega t)$$

using angular frequency
from above

SHM velocity

$$V = -A\omega \sin(\omega t)$$

Note: maximum velocity occurs when

$$\sin(\omega t) = 1$$

$$|V_{\max}| = A\omega \quad (\text{or maximum speed})$$

SHM Acceleration

$$a = -A\omega^2 \cos(\omega t)$$

Note: maximum acceleration occurs

$$\text{when } \cos(\omega t) = 1$$

$$|a_{\max}| = A\omega^2 \quad \left(\begin{array}{l} \text{magnitude of} \\ \text{or maximum} \\ \text{acceleration} \end{array} \right)$$

Spring-Mass Systems and Energy

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Period (T) for a spring-mass system

$$T = 2\pi \sqrt{\frac{m}{k}}$$

Angular frequency (ω) for a spring-mass system

$$\omega = \sqrt{\frac{k}{m}}$$

Energy Storage

$$E_{\text{Total}} = E_k + E_{el}$$

$$= \frac{1}{2}mv^2 + \frac{1}{2}kx^2$$

$$x = A \cos(\omega t)$$

$$v = -A\omega \sin(\omega t)$$

$$E_{Total} = \frac{1}{2} m (-A\omega \sin(\omega t))^2 + \frac{1}{2} k (A \cos \omega t)^2$$

$$= \frac{1}{2} m A^2 \omega^2 \sin^2(\omega t) + \frac{1}{2} k A^2 \cos^2(\omega t)$$

$$\omega = \sqrt{\frac{k}{m}} \Rightarrow \omega^2 = \frac{k}{m} \quad \text{for spring-mass system}$$

$$= \frac{1}{2} m A^2 \left(\frac{k}{m}\right) \sin^2(\omega t) + \frac{1}{2} k A^2 \cos^2(\omega t)$$

$$= \frac{1}{2} k A^2 (\sin^2(\omega t) + \cos^2(\omega t))$$

$$\sin^2 \theta + \cos^2 \theta = 1$$

$$E_{Total} = \frac{1}{2} k A^2$$