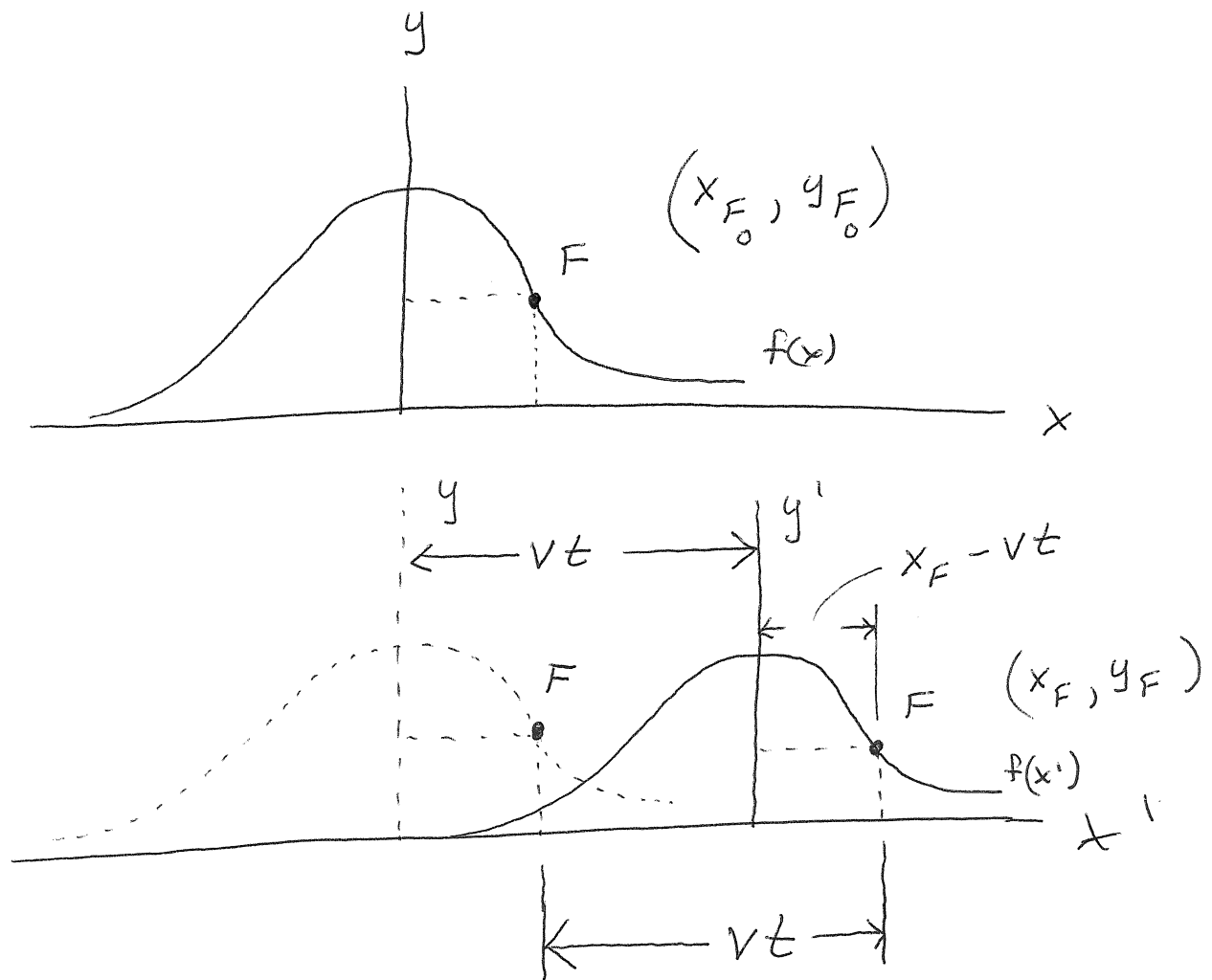


Mathematical Description of Waves

(1)



As a wave pulse travels through a medium without damping

$$y_{F_0} = y_F$$

* The wave shape does not change *

* Rather than shape change there is horizontal shift
 x_F increases as the pulse
 travels right

$$x_F = x_{F_0} + vt$$

← elapsed time

↑ pulse speed

Another way to think about the pulse
 is to describe it using $f(x)$ and
 $f(x')$ where the peak represents y
 and y' respectively.

$$y(x, 0) = f(x)$$

$$y(x, t) = f(x') = f(x - vt)$$

↑

Note: $x_t = x_0 + vt$
 $x_0 = x_t - vt$

(3)

No shape change \Rightarrow

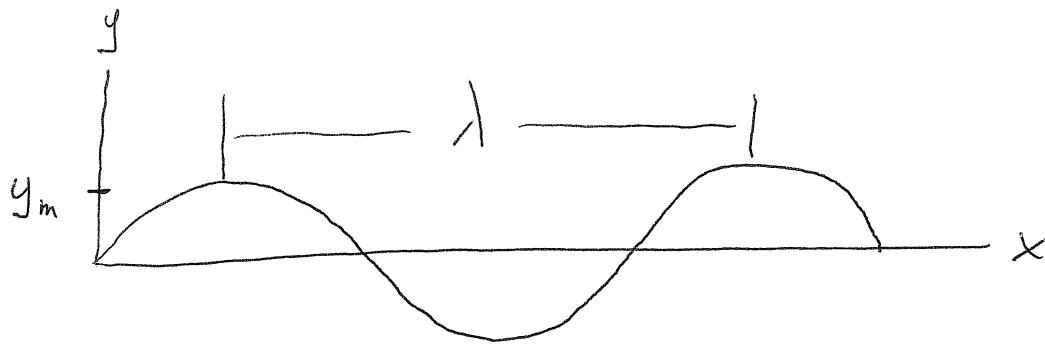
$$x - vt = \text{constant}$$

General Wave Equation

$$y(x, t) = f(x - vt)$$

* Any number of functions can fit
this form *

(4)



$$y(x, 0) = y_m \sin\left(\frac{2\pi}{\lambda} x\right)$$

As with a single pulse we can track a single point, eventually noting that we can use the general wave equation in this case.

$$y(x, t) = y_m \sin\left(\frac{2\pi}{\lambda} (x - vt)\right)$$

$$\lambda = v T$$

$T = \text{period (s)}$
 $v = \text{wavespeed (m/s)}$
 $\lambda = \text{wavelength (m)}$

$$\omega = \frac{2\pi}{T}$$

$\omega = \text{angular frequency (rad/s)}$

$$k = \frac{2\pi}{\lambda}$$

$k = \text{wave number (rad/m)}$

$$y(x, t) = y_m \sin(kx - \omega t)$$

$$\frac{2\pi}{\lambda} x = kx$$

$$\frac{2\pi}{\lambda} v t = \frac{2\pi}{\lambda} \left(\frac{\lambda}{T} \right) t = \omega t$$

